



Design and Analysis of Liner Forms for Shaft Sinking

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Abstract

Access to underground mines is in many cases through vertical shafts. If unstable ground conditions are encountered, the shaft walls are lined with concrete. The cylindrical concrete walls are formed with steel plates that are reinforced with circumferential and vertical stiffeners. The structural design and analysis of these forms is discussed in this paper. It is shown that stability of the forms, when subjected to pressures from the concrete during construction, is the governing criteria for the design. It is pointed out, that in order to obtain a safe design; some input parameters for the analysis have to be based on practical experience with liner construction in vertical shafts. An illustrative example is presented.

1. Introduction

Shaft sinking refers to the method of excavating a vertical or near-vertical tunnel from the surface down. Shaft sinking is one of the most difficult mine development methods and only a few companies have the expertise to perform this type of work. In North America most shafts are circular and lined with concrete. A concrete liner (or wall) is required in areas where the ground is unstable in order to contain any loose material and prevent it from falling down the shaft. The walls are shaped with steel forms and the concrete is poured behind these forms. Figure 1 shows the general arrangement of the liner installation.

The structural design of these forms is discussed in this paper and a numerical example is presented to illustrate the design procedure.

The important steps in the design are as follows.

- a. Determination of the geometry of the forms (based on shaft geometry)
- b. Selection of the material (steel)
- c. Determination of the loads on the forms
- d. Estimate of the response of the forms due to the applied loads by formulating an acceptable theoretical analysis model.
- e. Comparison of the resulting response with accepted yield and stability design limits
- f. By choosing appropriate safety factors against failure.

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The material presented here is based on Refs. 1 to 3, and has been edited and rearranged to suit the present topic and to make this paper useful as a design aid.

This paper is intended to be of use when checking liner forms and to assess that sufficient margins of safety have been provided in the design since safety is of paramount importance in the mining industry.

2. Applied Loads on the Forms

The applied loads are the dead weight of the forms and the lateral pressure from the concrete on the forms when the concrete is poured into the forms.

The radial, or lateral, pressure from the concrete is estimated by using the recommendations of ACI 347 (Ref. 1 and Ref. 2). These formulas are applicable and sufficiently accurate for the present application.

$$p = 150 + 9000 R/T \quad \text{if } R \leq 7 \text{ feet per hour} \quad (1)$$

$$p = C_w C_c (150 + 43500/T + 2800 R/T) \quad \text{if } R > 7 \text{ feet per hour} \quad (2)$$

with a max pressure of $2000 C_w C_c$ and a min pressure of $600 C_w$, but never more than $w.h$

where

p = lateral pressure on the forms (lbs/ft²)

C_w = unit weight coefficient ($C_w = 1$ for normal weight concrete)

C_c = 1.0 (for type I and III cement without retarders)

T = temperature of concrete, deg. F

R = rate of placement, feet per hour

w = unit weight of concrete, pcf

h = depth of fluid or plastic concrete from top of placement to the point of consideration, feet

A realistic estimate of the rate R of concrete pour is the critical assumption. This rate is obtained from previous experience of the shaft sinking contractor and depends on shaft diameter, thickness of liner, over break, depth of shaft and work schedule. In most cases this rate is proprietary information of the mining contractor.

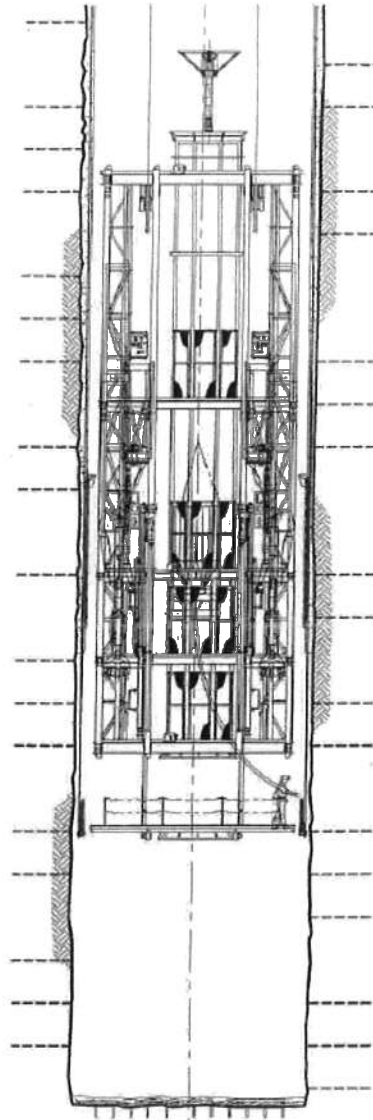


Figure 1: Shaft Sinking General Arrangement

3. Analysis Model

The forms are modeled as cylindrical shells with interior circumferential stiffeners. Although vertical stiffeners are also provided in practice, they can be neglected in the analysis

$$\text{if } \frac{s}{t} > 3 \left(\frac{r}{t}\right)^{\frac{1}{2}} \quad \text{for light vertical stiffeners} \quad (3)$$

The analysis will therefore neglect the longitudinal stiffeners when ring response is considered. Their presence will however be considered in the shell response, since they add a degree of conservatism to the results, in that they help to increase the shell buckling limit.

The basic geometric shell parameters are shown in Figure 2.

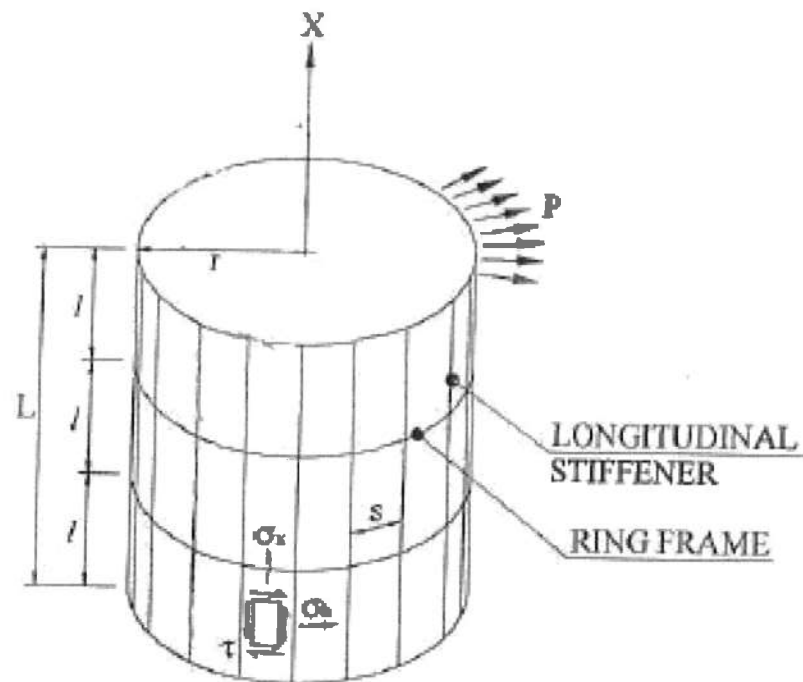


Figure 2: Cylinder Geometry (Ref. 3)

4. Stresses in Ring Stiffened Cylindrical Shells

4.1 Ring Stiffened Cylinder

In a ring stiffened cylinder (without longitudinal stiffeners) the circumferential membrane stress midway between two ring frames is

$$\sigma_h = \frac{pr}{t} - \frac{\alpha\zeta}{\alpha+1} \left(\frac{pr}{t} - \nu\sigma_x \right) \quad (4)$$

where

$$\zeta = 2 \frac{\sinh \beta \cos \beta + \cosh \beta \sin \beta}{\sinh 2\beta + \sin 2\beta}, \quad \zeta \geq 0 \quad (5)$$

$$\beta = \frac{l}{1.56 \sqrt{rt}} \quad (6)$$

$$\alpha = \frac{A_R}{l_{eo} t} \quad (7)$$

$$l_{eo} = \frac{l \cosh 2\beta - \cos 2\beta}{\beta \sinh 2\beta + \sin 2\beta} \quad (8)$$

ζ and l_{eo} may be obtained from Fig.3, or simply

$l_{eo} = l$ or $l_{eo} = 1.56 (rt)^{1/2}$, whichever is smaller

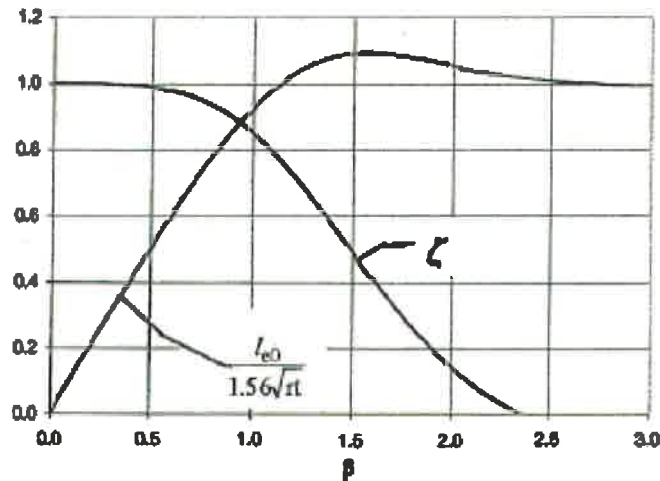


Figure 3: The Parameters l_{eo} and ζ (Ref. 3)

4.2 Ring Frame

The circumferential membrane stress at a ring frame for a ring stiffened cylinder (without longitudinal stiffeners) is

$$\sigma_{nR} = \left(\frac{pr}{t} - \nu \sigma_x \right) \frac{1}{1 + \alpha} + \nu \sigma_x \quad (9)$$

4.3 Design Longitudinal Membrane

The design longitudinal membrane stress is

$$\sigma_x = \sigma_a \quad (10)$$

where σ_a is due to the uniform axial force. In the present application this is the weight of the forms.

For a cylindrical shell without longitudinal stiffeners

$$\sigma_a = \frac{N_s}{2\pi r t} \quad (11)$$

4.4 Bending Stresses

Bending stresses and associated shear stresses will occur in the vicinity of discontinuities such as frames. The longitudinal bending stress in the shell at a ring frame is

$$\sigma_{xm} = \left(\frac{pr}{t} - \sigma_{hR} \right) \sqrt{\frac{3}{1-\nu}} \quad (12)$$

where σ_{hR} is given in Eq. (9)

4.5 Circumferential Bending Stress

The circumferential bending stress in the shell at a ring frame is

$$\sigma_{hm} = \nu \sigma_{xm} \quad (13)$$

5. Buckling Strength of Shells

The methods of buckling analysis are semi-empirical because agreement between theoretical and experimental buckling loads for some cases is difficult to establish. This discrepancy is due to the effect of geometric imperfections and residual stresses in fabricated shell structures. Geometric imperfections and residual stresses do not appear as explicit parameters in the theoretical buckling formulas. The methods of buckling analysis are therefore based on an assumed level of imperfections.

Stiffened cylindrical shells have to be designed to avoid several buckling failure modes. The relevant modes are as follows.

- a. Shell buckling: buckling of shell plating between rings and longitudinal stiffeners
- b. Panel stiffener buckling: Buckling of shell plating including longitudinal stiffeners. Rings are nodal lines.

- c. Panel ring buckling: Buckling of shell plating including rings. Longitudinal stiffeners act as nodal lines.
- d. General buckling: Buckling of shell plating including longitudinal stiffeners and rings.
- e. Local buckling of longitudinal stiffeners and rings.

In the present application we shall consider only a., c. and e. as possible failure modes.

5.1 Elastic Buckling Strength of Unstiffened Curved Panels

The elastic buckling strength of the curved panel between stiffeners and with aspect ratio of $l/s > 1$ is

$$f_B = C \left\{ \frac{\pi^2 E}{12(1 - \nu^2)} \right\} \left(\frac{t}{s} \right)^2 \quad (14)$$

The buckling coefficient is

$$C = \psi \left\{ 1 + \left(\frac{\rho \xi}{\psi} \right)^2 \right\}^{\frac{1}{2}} \quad (15)$$

where

$$\psi = \left\{ 1 + \left(\frac{s}{l} \right)^2 \right\}^2 \quad \xi = 1.04 \left(\frac{s}{l} \right) (Z_s)^{\frac{1}{2}} \quad \rho = 0.6 \quad (16)$$

The curvature parameter Z_s is defined as

$$Z_s = \left(\frac{s^2}{rt} \right) (1 - \nu^2)^{\frac{1}{2}} \quad (17)$$

A curved panel with aspect ratio $l/s < 1$ can be taken as an unstiffened circular cylindrical shell with length l . The buckling radial pressure is approximately (Ref. 4)

$$p_{cr} = 0.807 \left(\frac{Et^2}{lr} \right) \left\{ \left[\frac{1}{1 - \nu^2} \right]^3 \left(\frac{t}{r} \right)^2 \right\}^{\frac{1}{4}} \quad (18)$$

and the buckling stress is

$$f_B = p_{cr} \left(\frac{r}{t} \right) \quad (19)$$

5.2 Panel Ring Buckling

5.2.1 Initial Assumptions

In order to aid the designer with initial assumptions on the geometric parameters of the shell and ring stiffeners the following steps are offered as guides.

The cross sectional area of the ring frame to avoid panel ring buckling (exclusive of shell plate portion) should not be less than

$$A_{req} \geq \left(\frac{2}{(Z_l)^2} + 0.06 \right) l t \quad (20)$$

$$Z_l = \frac{l^2}{rt} (1 - \nu^2)^{\frac{1}{2}} \quad (21)$$

The effective moment of inertia of the ring frame (inclusive of the effective shell portion) should not be less than

$$I_h = \left(\frac{pr(r_0)^2 l}{3E} \right) \left[1.5 + \frac{3E z_t \theta_0}{(r_0)^2 (0.5 f_r - \sigma_{hR})} \right] \quad (22)$$

where the effective width of the shell plating to be included in the moment of inertia should be taken as the smaller of

$$l_{ef} = \frac{1.56(rt)^{\frac{1}{2}}}{1 + \frac{12l}{r}} \quad (23)$$

$$\text{or } l_{ef} = l$$

and the characteristic material resistance coefficient f_r is $\left(\frac{f_r}{2} > \sigma_{hR} \right)$

and $f_r = f_T$ for fabricated ring frames

$f_r = 0.9 f_T$ for cold formed ring frames

The torsional buckling strength f_T may be taken equal to the yield strength if the following requirements are satisfied

$$h \leq 0.4 t_w \left(\frac{E}{f_y} \right)^{\frac{1}{2}} \quad (24)$$

for flat bar ring frames and

$$h \leq 1.35 t_w \left(\frac{E}{f_y} \right)^{\frac{1}{2}} \quad (25)$$

$$b \geq \frac{7h}{\left\{ 10 + \left(\frac{Eh}{f_y r} \right) \right\}^{\frac{1}{2}}} \quad (26)$$

for flanged ring frames.

The assumed mode of deformation of the ring frame corresponds to ovalization and the initial out-of-roundness is defined by

$$w_0 = \partial_0 \cos 2\theta, \quad (27)$$

$$\partial_0 = 0.005 r \quad (28)$$

5.2.2. Buckling Stress in Ring Stiffened Cylindrical Shells

The elastic buckling strength is expressed as

$$f_E = C_1 \left[\frac{\pi^2 E}{12(1 - \nu^2)} \right] \left(\frac{t}{L} \right)^2 \quad (29)$$

Where

$$C_1 = \frac{2(1 + \alpha_B)}{1 + \alpha_B} \left\{ 1 + \frac{0.27 Z_L}{(1 + \alpha_B)^{\frac{1}{2}}} \right\}^{\frac{1}{2}} - \frac{\alpha_B}{1 + \alpha_B} \quad (30)$$

$$Z_L = \left(\frac{L^2}{rt} \right) (1 - \nu^2)^{\frac{1}{2}} \quad (31)$$

$$\alpha_B = \frac{12(1 - \nu^2) I_h}{l t^3} \quad (32)$$

5.2.3 Local Buckling of Ring Stiffeners

To prevent local buckling, ring stiffeners should be proportioned as follows

$$\text{Flat bar ring frames} \quad h \leq 0.4 t_w \left(\frac{E}{f_y} \right)^{\frac{1}{2}} \quad (33)$$

$$\text{Flanged ring frames} \quad h \leq 1.35 t_w \left(\frac{E}{f_y} \right)^{\frac{1}{2}} \quad (34)$$

6. Design Criteria

The final design of the forms should satisfy the following design criteria:

- a. Stress limits: The estimated shell and stiffener stresses should not exceed one half of the yield stress of the material.
- b. Stability limits: The estimated shell and stiffener stresses should not exceed one half of the lowest buckling stress.

7. Geometry of Ring Stiffener

A general ring cross section is shown in Fig. 4

The centroid of the ring frame including the effective shell width l_{eo} is at point A.

The centroid of the ring frame excluding the shell is at point B.

The centroid of the stiffener flange is at point C.

Symbols not defined in the text:

A_R Cross sectional area of the ring frame (exclusive of shell flange)

E Young's modulus

I_h Minimum required moment of inertia of ring frame inclusive effective shell flange

L Distance between effective supports of the ring stiffened cylinder

N_s Axial design load

f_r Material strength

f_T Torsional buckling strength

f_y Material yield strength

l Distance between rings

p Lateral design pressure on the forms

p_{cr} Buckling pressure

r Cylinder radius

s Distance between longitudinal stiffeners

t Shell thickness

δ_0 Initial out of roundness parameter

ν Poisson's ratio = 0.3

Θ Circumferential coordinate

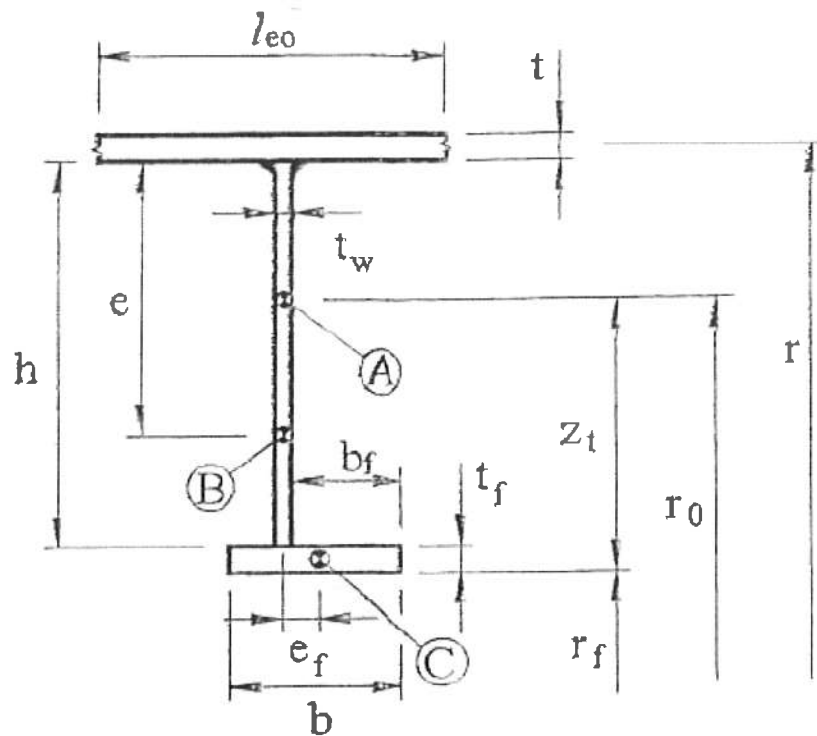


Figure 4: Stiffener Geometry (Ref. 3)

References

1. American Concrete Institute, Committee 347, (ACI 347-01), "Guide to Formwork for Concrete".
2. Concrete Construction, Nov.1994, Problem Clinic, "Lateral Pressure on one-sided Wall Forms".
3. Det Norske Veritas, Recommended practice DNV-RP-C202, Oct. 2010, "Buckling Strength of Shells".
4. R. Roark and R. W. Young, Formulas for Stress and Strain, McGraw Hill.

APPENDIX

Numerical Example

Photos courtesy of PROMAIN, Proyecto Manufacture Industrial S.A., Hermosilla, Sonora, Mexico.

DESIGN PARAMETERS:

- Shaft diameter = 20 ft
- Form height = 20 ft
- Material ASTM A36
- Representative panel geometry Fig. A-2
- Concrete rate of pour = 3.0 ft per hr.
- Concrete temp. = 100°F

LOADS ON FORMS:

- Pressure from concrete

$$p = 150 + \frac{42500}{100} + 2000 \cdot \frac{3}{100} = 670 \text{ psf}$$

$$\approx 4.6 \text{ psi}$$
- Vertical load = dead weight of forms
 estimated @ 1000 lbs / 4 circumference
 (or $\sigma_x = 333 \text{ psi}$)

ANALYSIS MODEL: Fig. A-1

$l = 24 \text{ in}$, $s = 23 \text{ in}$, $r = 132 \text{ in}$, $t = 0.25 \text{ in}$

$$\frac{23}{0.25} > 3 \sqrt{\frac{132}{0.25}}$$

$$92 > 69$$

∴ can neglect vert. stiffeners
in ring response

STRESSES IN RING STIFFENED SHELL:

- a) Circular membrane stress midway between two rings
 $l = 24 \text{ in}$, $r = 132 \text{ in}$, $p = 4.6 \text{ psi}$, $t = 0.25 \text{ in}$
 $A_r = 1.97 \text{ in}^2$
 $l_e = \frac{1.56 \sqrt{132 \times 0.25}}{1} = 9 \text{ in}$
 $\beta = \frac{24}{9} = 2.7$
 $\alpha = \frac{1.97}{9 \times 0.25} = 0.88$

From Fig. 3:

$$l_e = 9 \text{ in OK}$$

$$\zeta = 0$$

$$\sigma_r = \frac{4.6 \times 132}{0.15} = 2430 \text{ psi}$$

CIRCULAR MEMBRANE STRESS IN RING:

$$\sigma_{r1} = \left[\frac{4.6 \times 132}{0.25} - 0.3 \times 333 \right] \frac{1}{1 + 0.88} + 0.3 \times 333 =$$

$$\sigma_{r1} = 1340 \text{ psi}$$

LONGITUDINAL MEMBRANE STRESS:

$$\sigma_x = 333 \text{ psi}$$

LONGITUDINAL BENDING STRESS AT RING

$$\sigma_{xm} = \left(\frac{4.6 \times 132}{0.25} - 1040 \right) \sqrt{\frac{3}{1 - 0.32}}$$

$$\sigma_{xm} = 1977 \text{ psi}$$

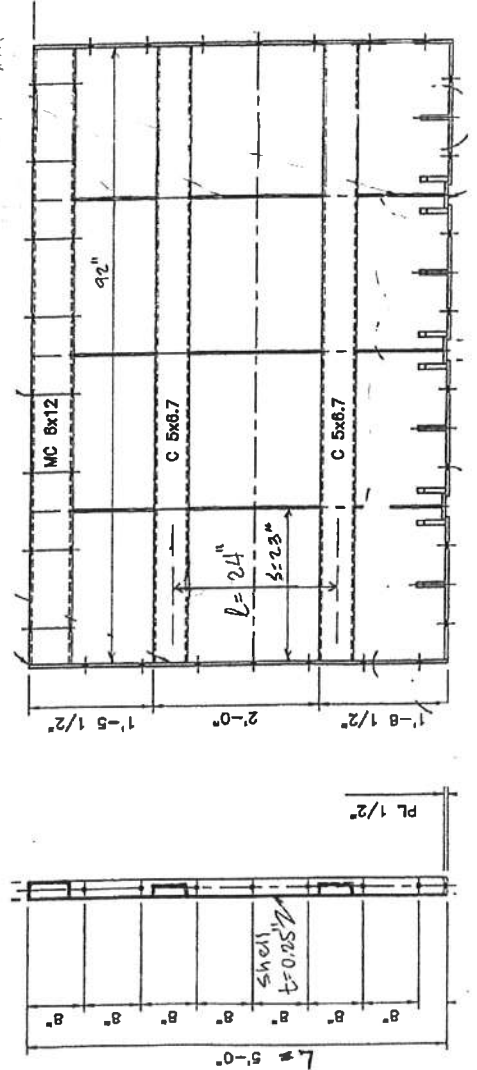


Fig. A-1

CIRCUMFERENTIAL BENDING STRESS AT RING

$$\sigma_{hm} = 0.3 \times 1977 = 593 \text{ psi}$$

BUCKLING OF CURVED PANEL:

$$k/s = \frac{24}{23} \approx 1.0$$

$$E = 29 \times 10^6 \text{ psi}$$

$$P_{cr} = 0.807 \frac{E \times 0.25^2}{24 \times 132} \left[\frac{1}{(1-\nu^2)} \left(\frac{0.25^2}{132} \right)^{1/4} \right]^2$$

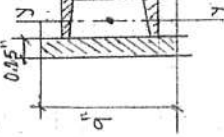
$$P_{cr} = 21.6 \text{ psi}$$

Buckling stress:

$$\sigma_{cr} = \frac{21.6 \times 132}{0.25} = 11,405 \text{ psi}$$

PANEL RING BUCKLING:

$$a = \frac{L^2}{9 \times 0.25} = 0.88$$



$$I_h = 2.5 \text{ in}^4$$

= moment of inertia of combined section about axis y-y

L = Height of form = 15 ft

$$\alpha_B = \frac{12(1-0.3^2)2.5}{24 \times 0.255} = 12.8$$

$$z_L = \frac{260^2}{152 \times 0.15} \sqrt{1-0.3^2} = 6.5$$

Buckling coefficient

$$C_1 = \frac{2(1+\nu)}{1+0.88} \left[\frac{1 + \frac{0.25 \times 16.5}{\sqrt{1+\nu \times 0.88}}}{1+70.8} \right]^2 =$$

$$C_1 = 0.6$$

Buckling stress

$$f_B = C_1 \frac{\pi^2 E}{12(1-\nu^2)} \left(\frac{0.25}{100} \right)^2 = 3910 \text{ psi}$$

SUMMARY

- Wire membrane in shell 2450 psi
- Circ. membrane in ring 13470 psi
- Long membrane in shell 333 psi
- Circ. bending at ring 593 psi
- Long bending at ring 1977 psi
- Buckling stress of shell 11,405 psi
- Buckling stress of panel ring 3910 psi

